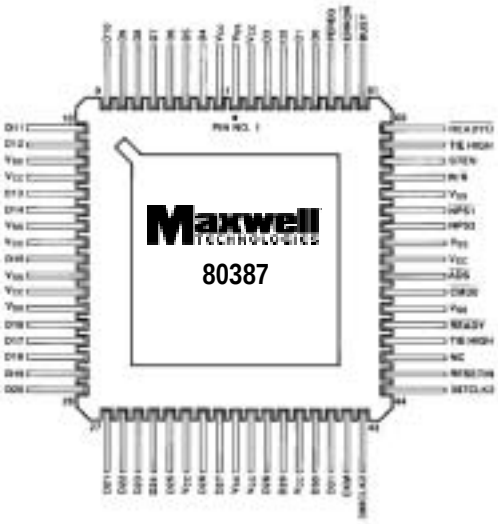
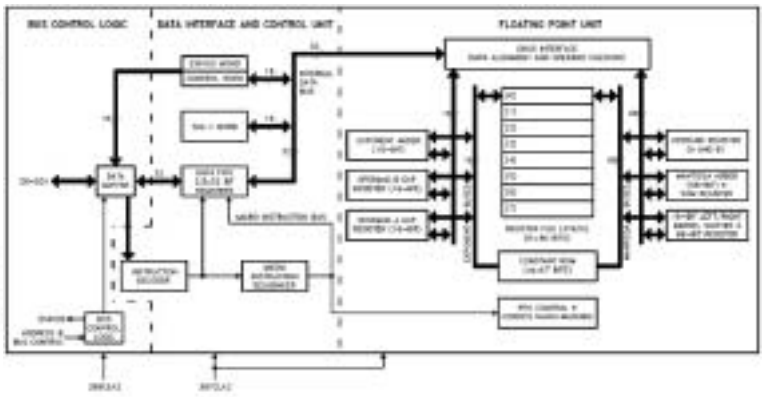
80387DX
Math Coprocessor





Logic Diagram

FEATURES:

- 80-Bit numeric processor
- RAD-PAK® radiation hardened against natural space radiation
- Total dose hardness:
  - > 100 krad (Si)
  - dependant upon space mission
- Single Event Effects:
  - SEU Threshold is ~ 3.38 MeV/mg/cm^2
  - SEL Threshold = 37.1 - 59.9 MeV/mg/cm^2
- Package: 68-pin RAD-PA® quad flat pack
- Eight 80-bit numeric registers, usable as individual addressable general registers or as a register stack
- Data types include:
  - 32-, 64-, 80-bit floating point
  - 32-, 64-bit integers
  - 18-digit BCD operands
- 5 V Only power
- Built-in exception handling
- Upward object code compatible with All 80X87DX microprocessors
- Full-range transcendental operations for SINE, COSINE, TANGENT, ARCTANGENT and LOGARITHM

DESCRIPTION:

Maxwell's 80387DX high speed microcircuit features a greater than 100 kilorad (Si) total dose tolerance. Using Maxwell's radiation hardened RAD-PAK® packaging technology, the 80387DX is a high-performance numerics processor that extends the 80386DX architecture with floating point, extended integer and BCD data types. The computing system fully conforms to the ANSI/IEEE floating-point standard. Using a numerics oriented architecture, the 80387DX adds over seventy mnemonics to the 80386DX instruction set, making the 80386DX/80387DX a complete solution for high-performance numerics processing.

Maxwell Technologies' patented RAD-PAK packaging technology incorporates radiation shielding in the microcircuit package. It eliminates the need for box shielding while providing the required radiation shielding for a lifetime in orbit or space mission. In a GEO orbit, RAD-PAK provides greater than 100 krad (Si) radiation dose tolerance. This product is available with screening up to Class S.

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TABLE 1. PINOUT DESCRIPTION

PIN	SYMBOL	DESCRIPTION
1, 12, 19, 21, 35, 49, 53, 56	V_{SS}	Ground
2, 13, 20, 32, 36, 39, 52, 68	V_{CC}	Positive Power Supply
3-11, 18, 22-31, 33, 34, 37, 38, 40, 41, 64-67	D4-D12, D15, D16-25, D26, D27, D28, D29, D30, D31, D0-D3	Data Bus
42	CKM	Clock Mode
43	386CLK2	386 CPU Clock 2
44	387CLK2	387 MCP Clock 2
45	RESETIN	System Reset
46	NC	Not Connected
47 59	Tie High	Tie High
48	$\overline{\text{READY}}$	Bus Ready Input
50	$\overline{\text{CMD0}}$	Command
51	$\overline{\text{ADS}}$	Address Strobe
54	NPS2	MCP Select #2
55	$\overline{\text{NPS1}}$	MCP Select #1
57	W/$\overline{\text{R}}$	Write/Read
58	STEN	Status Enable
60	$\overline{\text{READYO}}$	Ready Output
61	$\overline{\text{BUSY}}$	Busy Status
62	$\overline{\text{ERROR}}$	Error Status
63	PEREQ	Processor Extension Request

TABLE 2. ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	MIN	MAX	UNIT
Voltage, any pin, with respect to Ground	V_{CC}	-0.5	V_{CC}+0.5	V
Power Dissipation	P_D	--	1.5	W
Storage Temperature Range	T_S	-65	150	˚C
Operating Temperature Range	T_A	-55	125	˚C
Lead Temperature (soldering 10 seconds)		--	260	˚C

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TABLE 3. DELTA LIMITS

PARAMETER	VARIATION
I_{LI}	± 1.5 µA
I_{LO}	±1.5 µA
I_{CC} CLK2 = 32 MHz	±25 mA
I_{CC} CLK2 = 50 MHz	±39 mA

TABLE 4. RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	MIN	MAX	UNIT
Supply Voltage	V_{CC}	4.75	5.25	V
Input Low Voltage	V_{IL}	-0.3	0.8	V
Input High Voltage	V_{IH}	2.0	V_{CC} +0.3	V
Operating Temperature	T_A	-55	125	°C

TABLE 5. 80387DX DC ELECTRICAL CHARACTERISTICS

(V_{CC} = 4.75V TO 5.25V; T_A = -55 TO +125°C, UNLESS OTHERWISE SPECIFIED)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	MAX	UNIT
Input Low Voltage	V_{IL}[1]		-- --	0.8 --	V
Input High Voltage	V_{IH}[1]		2.0	--	V
386 CLK2 Input Low Voltage	V_{CL}		--	0.8	V
386 CLK2 Input High Voltage	V_{CH}		3.7	--	V
Output Low Voltage	V_{OL}	I_{OL} = 4 mA, D0-D31, I_{OL} = 2.5 mA READYO , ERROR, BUSY, PEREQ	--	0.45	V
Output High Voltage	V_{OH}	I_{OH} = -1 mA, D0-D31, I_{OH} = -0.6 mA READYO, READYO, ERROR, BUSY, PEREQ	2.4	--	V
Input Leakage Current	I_{LI}	$0V \le V_{IN} \le V_{CC}$		±15	µA
Output Leakage Current	I_{LO}	$0.45V \le V_{OUT} \le V_{CC}$	--	±15	µA
Power Supply Current	I_{CC}	CLK2 = 32 MHz CLK2 = 40 MHz CLK2 = 50 MHz[2]	-- -- --	250 310 390	mA
Input Capacitance[3]	C_{IN}	F_C = 1 MHz	--	10	pF
Output Capacitance[3]	C_O	F_C = 1 MHz	--	12	pF
CLK2 Capacitance[3]	C_{CLK}	F_C = 1 MHz	--	20	pF

1. This parameter is for all inputs, including 387CLK2 but excluding 386CLK2.
2. Icc is measured at steady state, maximum capacitive loading on the outputs, and worst-case DC level at the inputs; 386CLK2 at the same frequency as 387CLK2.
3. Guaranteed By Design

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TABLE 6. 80387DX COMBINATIONS OF BUS INTERFACE AND EXECUTION SPEEDS

(V_{CC} = 4.75V TO 5.25V; T_A = -55 TO +125°C, UNLESS OTHERWISE SPECIFIED)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	MAX	UNIT
Bus INterface Unit					MHz
-16			16	--	
-20			20	--	
-25			25	--	
Execution Unit					MHz
-16			16	--	
-20			20	--	
-25			25	--	

TABLE 7. 80387DX TIMING REQUIREMENTS OF THE EXECUTION UNIT

(V_{CC} = 4.75V TO 5.25V; T_A = -55 TO +125°C, UNLESS OTHERWISE SPECIFIED)

PARAMETER	SYMBOL	TEST CONDITION	MIN	MAX	UNIT
387CLK2 Period[1]	t_1	At 2V			ns
-16			31	125	
-20			25	125	
-25			20	125	
387CLK2 High Time	t_{2a}	At 2V			ns
-16			9	--	
-20			8	--	
-25			7	--	
387CLK2 High Time[1]	t_{2b}	At 3.7V			ns
-16			5	--	
-20			5	--	
-25			4	--	
387CLK2 Low Time	t_{3a}	At 2V			ns
-16			9	--	
-20			8	--	
-25			7	--	
387CLK2 Low Time[1]	t_{3b}	At 0.8V			ns
-16			7	--	
-20			6	--	
-25			5	--	
387CLK2 Fall Time[1]	t_4	At 3.7V to 0.8V			ns
-16			--	8	
-20			--	8	
-25			--	7	
387CLK2 Rise Time[1]	t_5	At 0.8V to 3.7V			ns
-16			--	8	
-20			--	8	
-25			--	7	

1. Guaranteed By Design

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TABLE 8. 80387DX TIMING REQUIREMENTS OF THE BUS INTERFACE UNIT (OUTPUT TRIP LEVEL = 1.5V)

(V_{CC} = 4.75V TO 5.25V; T_A = -55 TO +125°C, UNLESS OTHERWISE SPECIFIED)

PARAMETER	CONDITIONS	SYMBOL	MIN	MAX	UNIT
386CLK2 Period[1]	At 2.0V	t_1			ns
-16			31	125	
-20			25	125	
-25			20	125	
386CLK2 High Time	At 2.0V	t_{2a}			ns
-16			9	--	
-20			8	--	
-25			7	--	
386CLK2 High Time1	At 3.7V	t_{2b}			ns
-16			5	--	
-20			5	--	
-25			4	--	
386CLK2 Low Time	At 2V	t_{3a}			ns
-16			9	--	
-20			8	--	
-25			7	--	
386CLK2 Low Time[1]	At 0.8V	t_{3b}			ns
-16			7	--	
-20			6	--	
-25			5	--	
386CLK2 Fall Time[1]	At 3.7V to 0.8V	t_4			ns
-16			--	8	
-20			--	8	
-25			--	7	
386CLK2 Rise Time[1]	At 0.8V to 3.7V	t_5			ns
-16			--	8	
-20			--	8	
-25			--	7	
386 CLK2/387CLK2 Ratio		--	10/16	14/10	--
$\overline{\text{READYO}}$ Out Delay	C_L = 50 pF	t_7			ns
-16			4	34	
-20			3	31	
-25			3	24	
PEREQ, $\overline{\text{ERROR}}$ Out Delay	C_L = 50 pF	t_7			ns
-16			5	34	
-20			5	34	
-25			4	33	
$\overline{\text{BUSY}}$ Out Delay	C_L = 50 pF	t_7			ns
-16			5	34	
-20			5	29	
-25			4	29	

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TABLE 8. 80387DX TIMING REQUIREMENTS OF THE BUS INTERFACE UNIT (OUTPUT TRIP LEVEL = 1.5V)

(V_{CC} = 4.75V TO 5.25V; T_A = -55 TO +125°C, UNLESS OTHERWISE SPECIFIED)

PARAMETER	CONDITIONS	SYMBOL	MIN	MAX	UNIT
D31 - D0 Out Delay	C_L = 50 pF	t_8			ns
-16			1	54	
-20			1	54	
-25			0	50	
D31 - D0 Setup Time		t_{10}	11		ns
D31 - D0 Hold Delay		t_{11}	11		ns
D31 - D0 Float Time	C_L = 50 pF[2]	t_{12}			ns
-16			6	33	
-20			6	27	
-25			5	24	
$\overline{\text{PEREQ}}$, $\overline{\text{BUSY}}$, $\overline{\text{ERROR}}$, $\overline{\text{READYO}}$ Float Time[1]	C_L = 50 pF[1]	t_{13}			ns
-16			1	60	
-20			1	50	
-25			1	40	
$\overline{\text{ADS}}$, $\overline{\text{W/R}}$ Setup Time		t_{14}			ns
-16			26	--	
-20			21	--	
-25			16	--	
$\overline{\text{ADS}}$, $\overline{\text{W/R}}$ Hold Time		t_{15}			ns
-16			5	--	
-20			5	--	
-25			4	--	
$\overline{\text{READY}}$ SetupTime		t_{16}			ns
-16			21	--	
-20			12	--	
-25			9	--	
$\overline{\text{READY}}$ Hold Time		t_{17}			ns
-16			4	--	
-20			4	--	
-25			4	--	
$\overline{\text{CMDO}}$ SetupTime		t_{16}			ns
-16			21	--	
-20			19	--	
-25			16	--	
$\overline{\text{CMDO}}$ HoldTime		t_{17}			ns
-16			2	--	
-20			4	--	
-25			4	--	
$\overline{\text{NPS1}}$, NPS2 Setup Time		t_{16}			ns
-16			21	--	
-20			19	--	
-25			16	--	

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TABLE 8. 80387DX TIMING REQUIREMENTS OF THE BUS INTERFACE UNIT (OUTPUT TRIP LEVEL = 1.5V)

(V_{CC} = 4.75V TO 5.25V; T_A = -55 TO +125°C, UNLESS OTHERWISE SPECIFIED)

PARAMETER	CONDITIONS	SYMBOL	MIN	MAX	UNIT
$\overline{\text{NPS1}}$, NPS2 Hold Time		t_{17}			ns
-16			2	--	
-20			2	--	
-25			4	--	
STEN Setup Time		t_{16}			ns
-16			21	--	
-20			21	--	
-25			15	--	
STEN Hold Time		t_{17}			ns
-16			2	--	
-20			2	--	
-25			4	--	
RESETIN Setup Time		t_{18}			ns
-16			13	--	
-20			12	--	
-25			10	--	
RESETIN Hold Time		t_{19}			ns
-16			4	--	
-20			4	--	
-25			3	--	

1. Guaranteed By Design

2. Float condition occurs when maximum output current becomes less than I_{LO} in magnitude. Float Delay is not tested.

TABLE 9. 80387DX TIMING REQUIREMENT OF OTHER PARAMETER

PARAMETER	SYMBOL	MIN	MAX	UNIT
RESETIN Duration	t_{30}	40		(387 CLK2)
RESETIN Inactive to First Opcode Write	t_{31}	50		(387 CLK2)
$\overline{\text{BUSY}}$ Duration	t_{32}	6		(386 CLK2)
$\overline{\text{ERROR}}$ Inactive to $\overline{\text{BUSY}}$ Inactive	t_{33}	6		(386 CLK2)
PEREQ Inactive to $\overline{\text{ERROR}}$ Active	t_{34}	6		(386 CLK2)
$\overline{\text{READY}}$ Active to Busy Active	t_{35}	4	4	(386 CLK2)
$\overline{\text{READY}}$ Minimum Time from Opcode Write to Opcode to Opcode/ Operand Write	t_{36}	6		(386 CLK2)
$\overline{\text{READY}}$ Minimum Time from Operand Write to Operand Write	t_{37}	8		(386 CLK2)

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FIGURE 1. TIMING DIAGRAMS - FAST TRANSITIONS TO AND FROM PIPELINED CYCLES

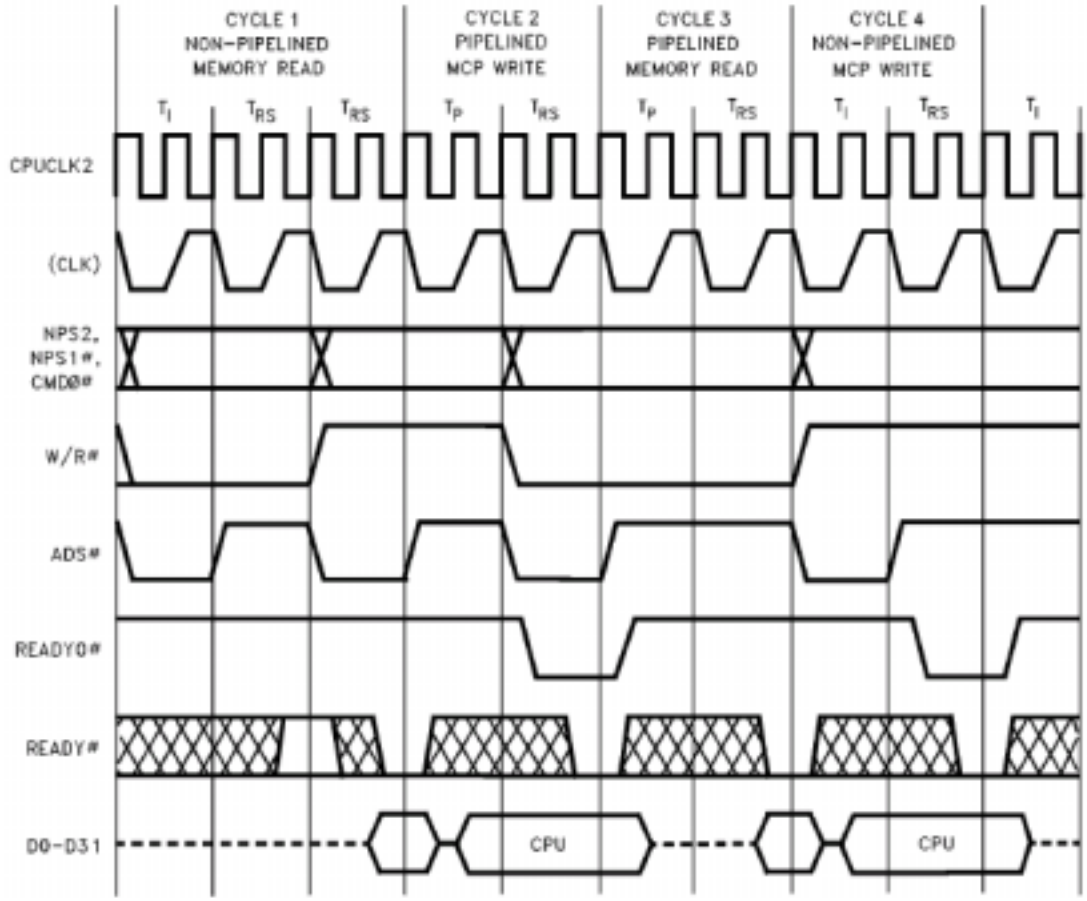

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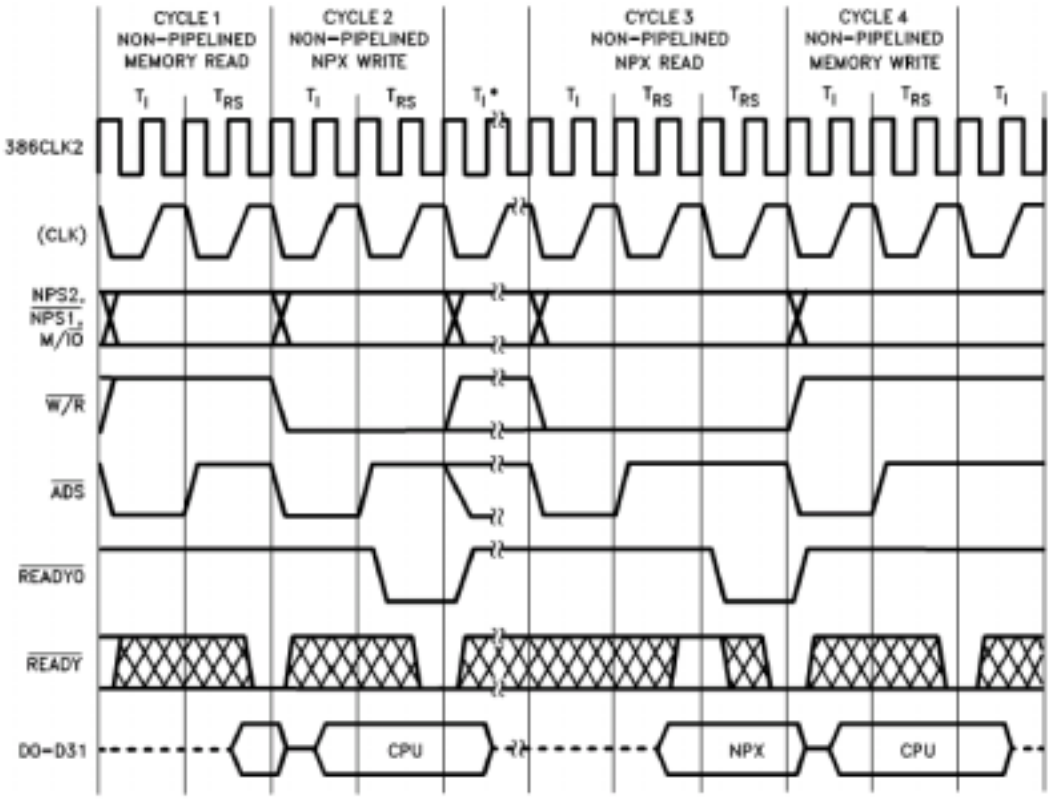
FIGURE 2. TIMING DIAGRAM – NON-PIPELINED READ AND WRITE CYCLES



Cycles 1 & 2 represent part of the operand transfer cycle for instructions involving either 4-byte or 8-byte operand loads.
Cycles 3 & 4 represent part of the operand transfer cycle for a store operation.
*Cycles 1 & 2 could repeat here or T_I states for various non-operand transfer cycles and overhead.

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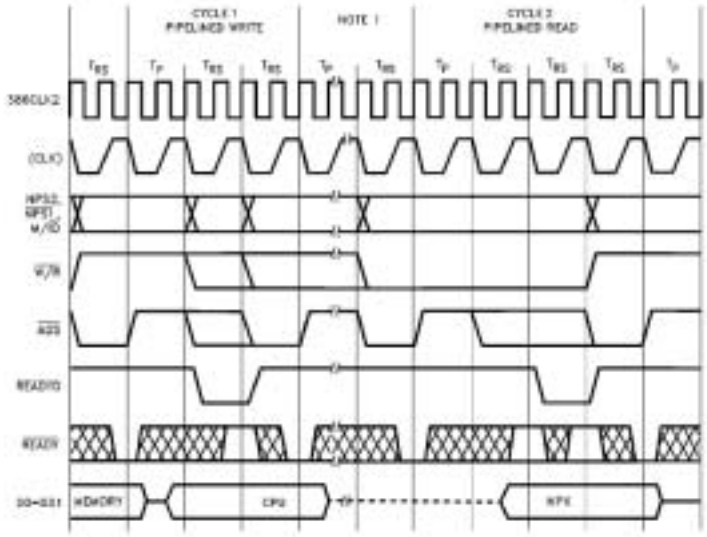
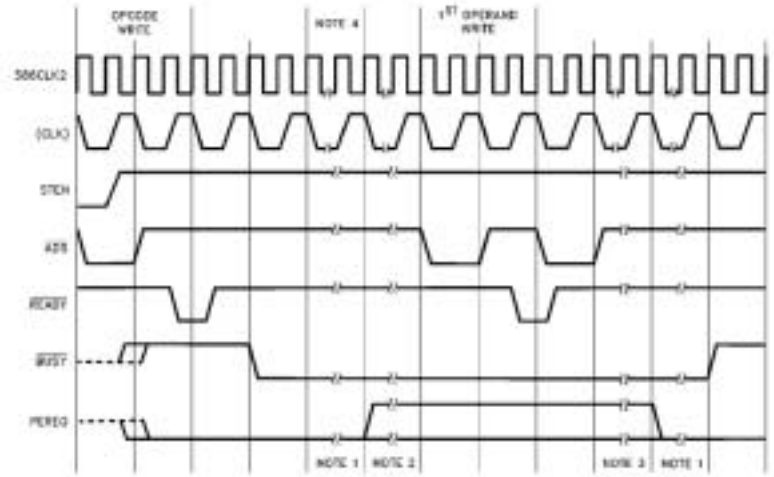
FIGURE 3. TIMING DIAGRAM – PIPLINED CYCLES WITH WAIT STATES



NOTE:
1. Cycles between operand write to the NPX and storing result.

FIGURE 4. TIMING DIAGRAM – STEN, BUSY, AND PEREQ TIMING RELATIONSHIP



NOTES:
1. Instruction dependent.
2. PEREQ is an asynchronous input to the 386 processor; it may not be asserted (instruction dependent).
3. More operand transfers.
4. Memory read (operand) cycle is not shown.

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FIGURE 5. TIMING DIAGRAM – 386CLK2/387CLK2 WAVEFORM AND MEASUREMENT POINTS FOR INPUT/ OUTPUT AC SPECIFICATIONS

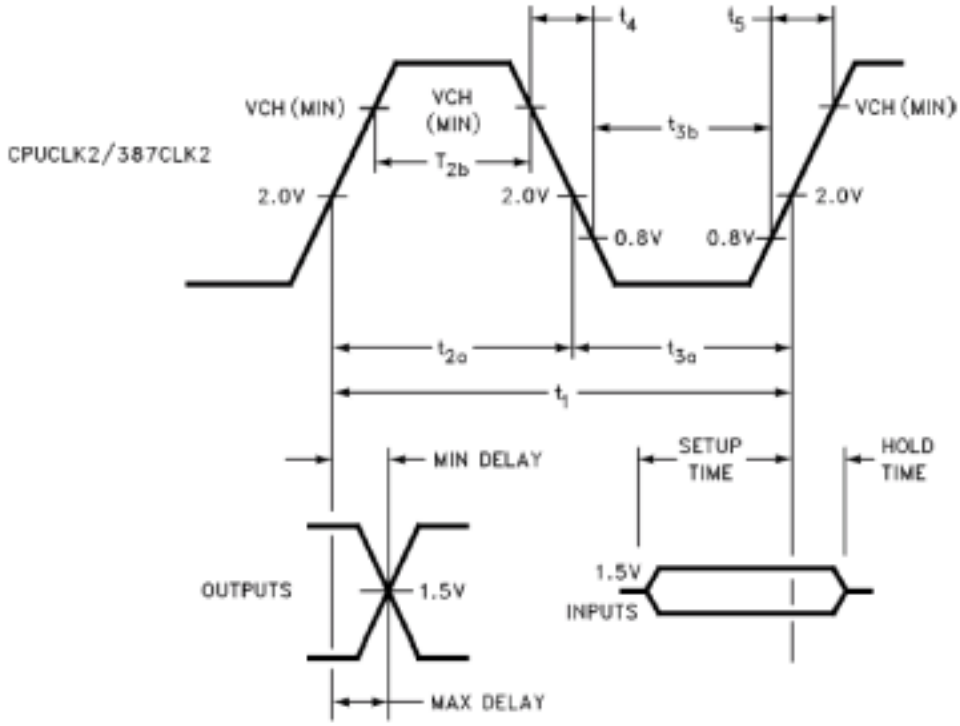

FIGURE 6. TIMING DIAGRAM – TEST CIRCUIT

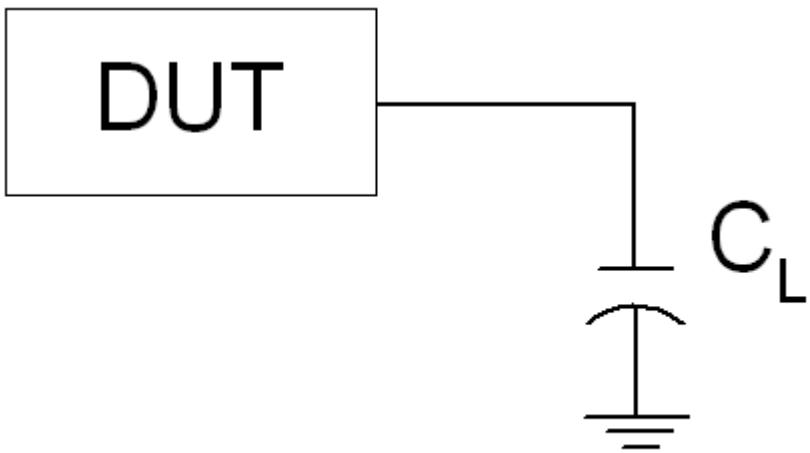

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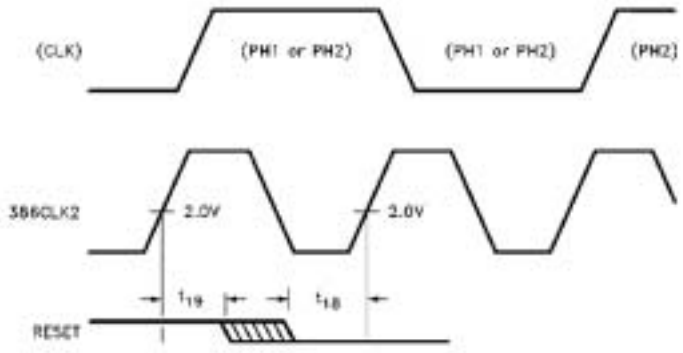
FIGURE 7. TIMING DIAGRAM – RESET



NOTE: The second internal processor phase following RESET high to low transition is PH2.

FIGURE 8. TIMING DIAGRAM – OUTPUT

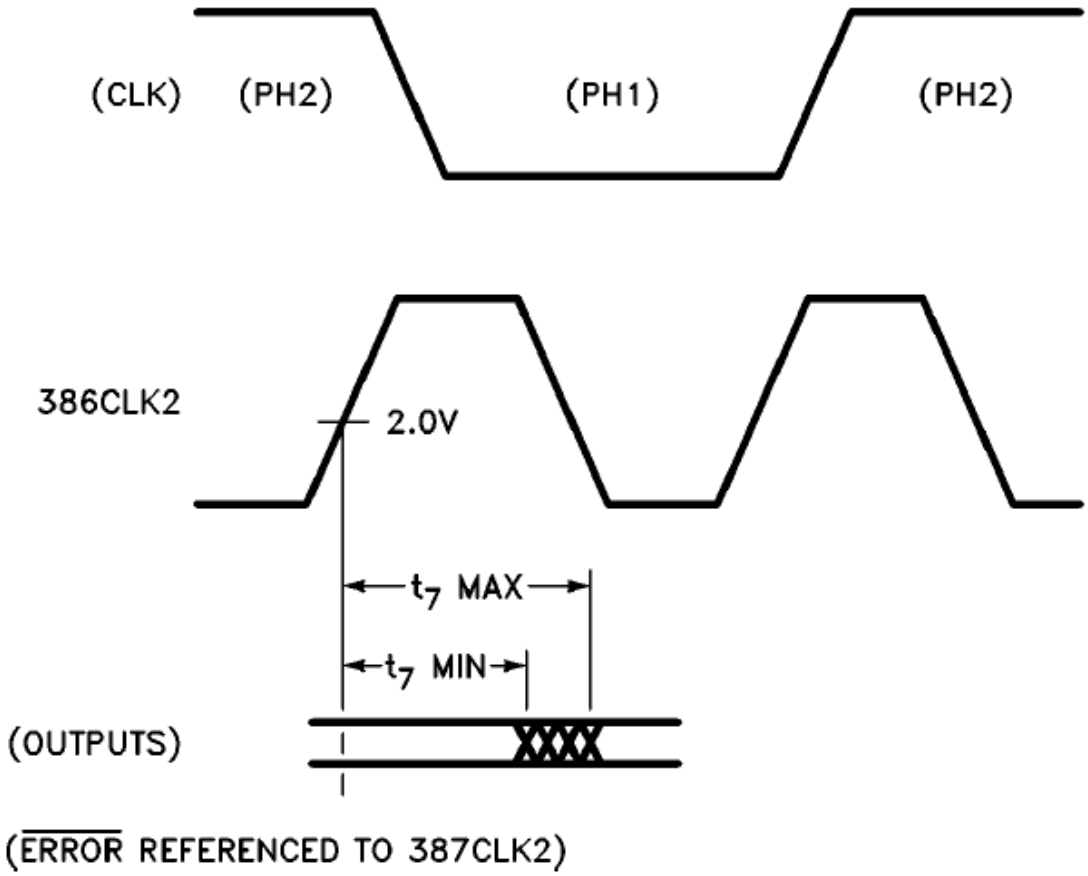


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FIGURE 9. TIMING DIAGRAM – INPUT AND I/O SIGNALS

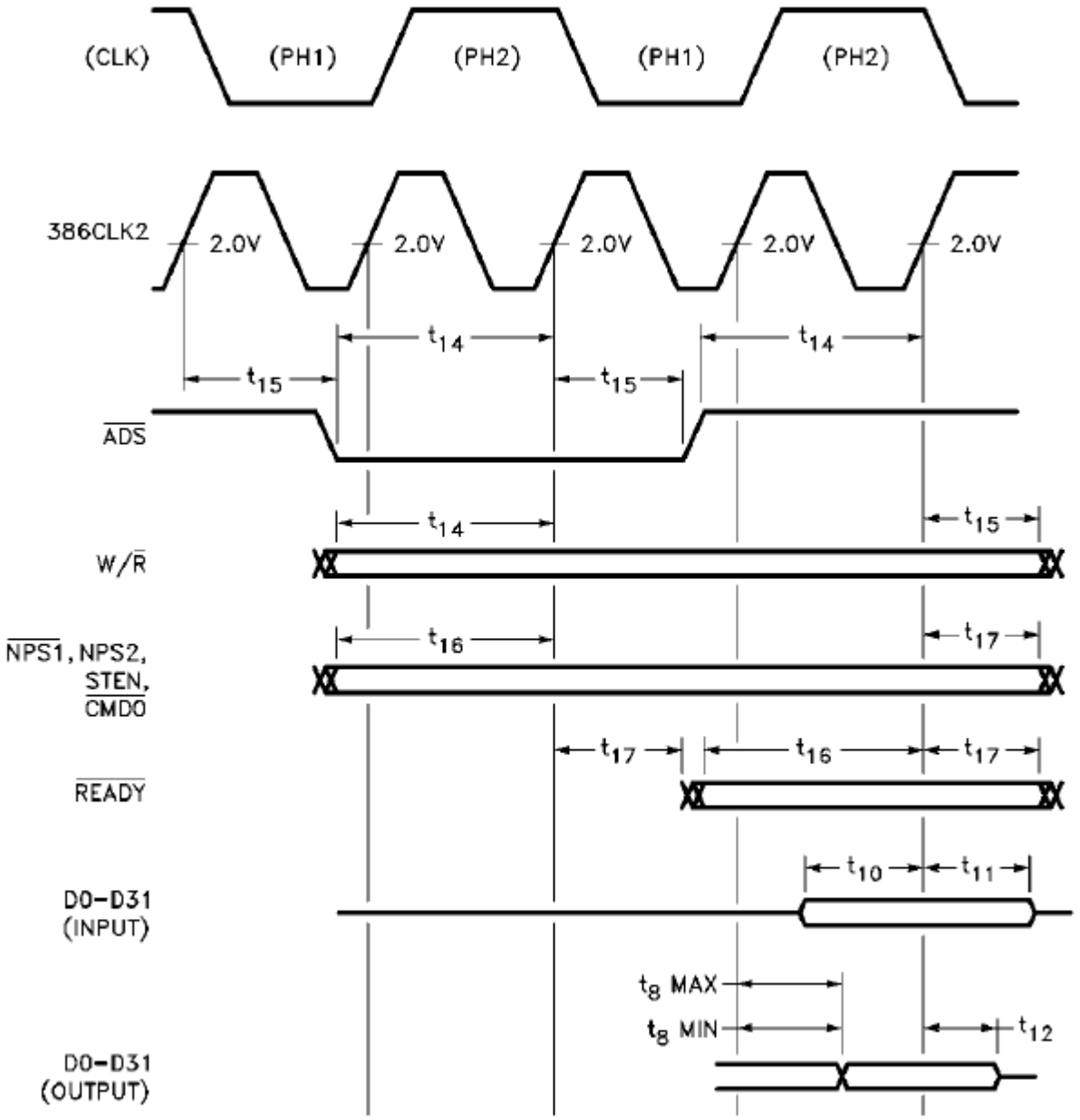

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FIGURE 10. TIMING DIAGRAM – FLOAT FROM STEN

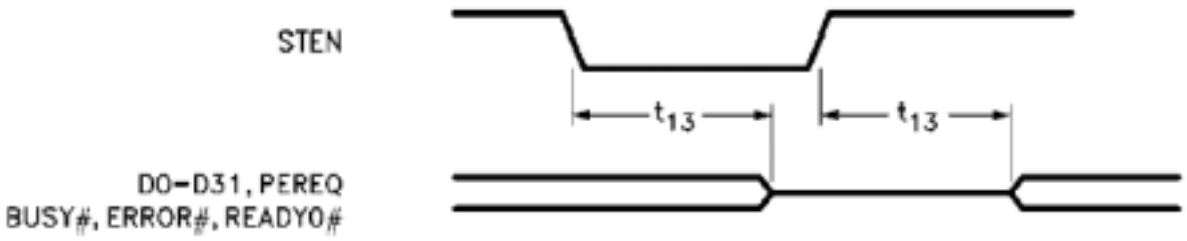
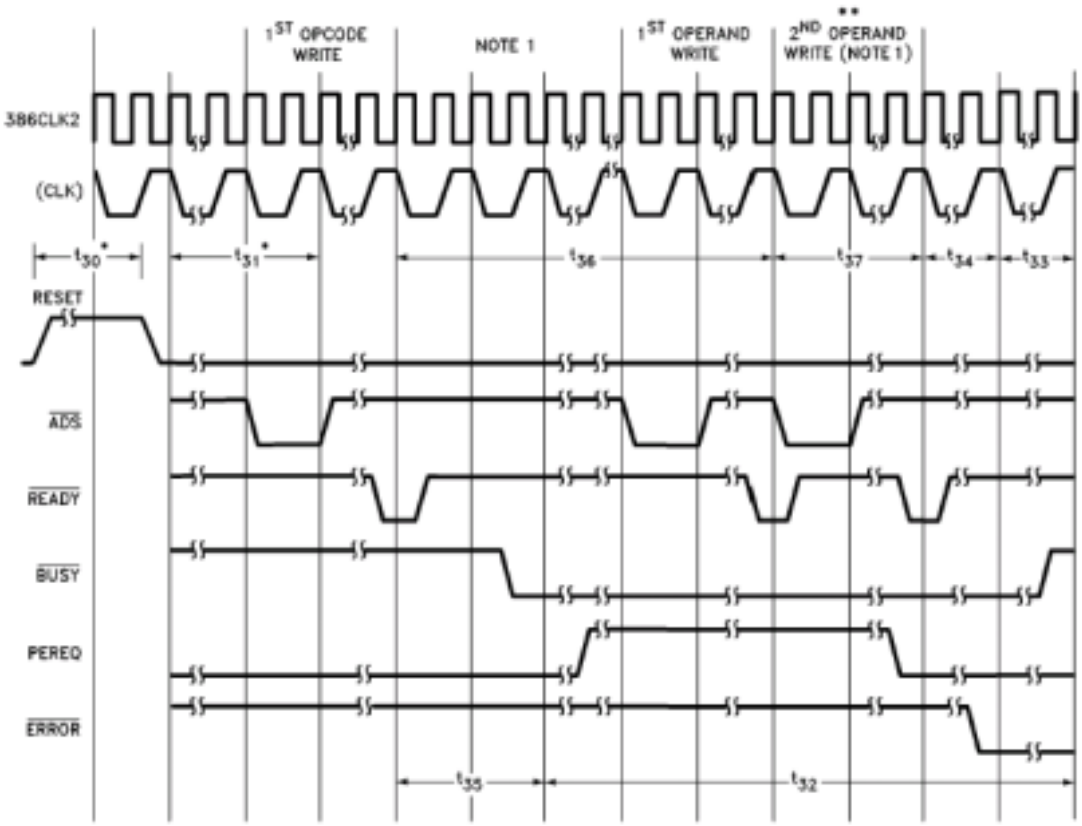


FIGURE 11. TIMING DIAGRAM – OTHER PARAMETERS



* In 387CLK2's
** or last operand

NOTE:
1. Memory read (operand) cycle is not shown.

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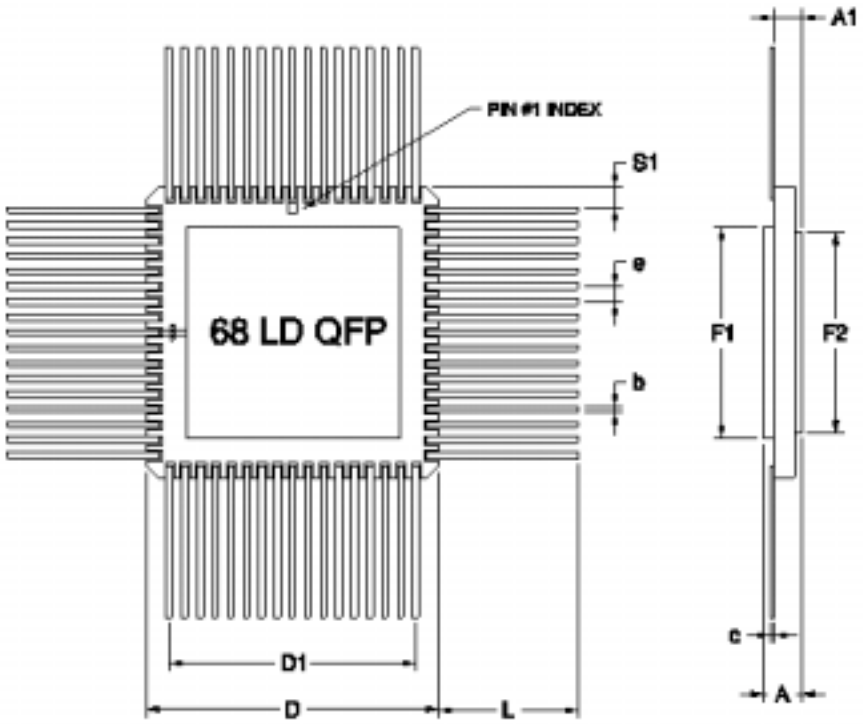

14 PIN RAD-PAK® FLAT PACKAGE

SYMBOL	DIMENSION		
	MIN	NOM	MAX
A	0.121	0.135	0.145
b	0.016	0.018	0.020
c	0.008	0.010	0.012
D	0.940	0.950	0.960
D1		0.800 BSC	
e		0.050 BSC	
S1	0.013	0.066	--
F1	0.645	0.650	0.655
F2	0.645	0.650	0.655
L	0.477	0.487	0.497
A1	0.080	0.090	0.100
N		68	

Note: All dimensions in inches.
Q68-01

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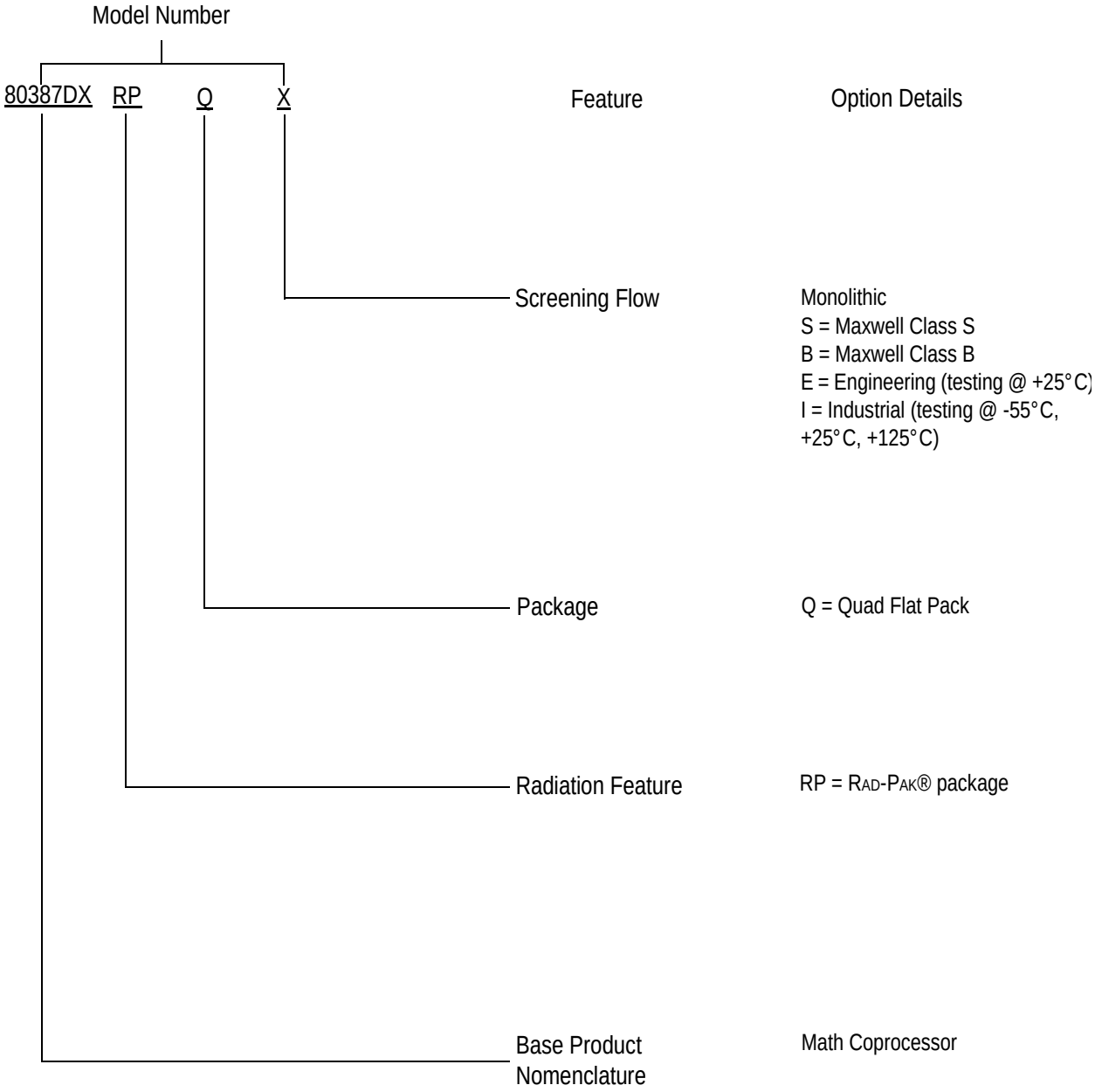

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- Индивидуальный подход
- Гибкое ценообразование

Наша организация особенно сильна в поставках модулей, микросхем, пассивных компонентов, ксайленсах (XC), EPF, EPM и силовой электроники.

Большой выбор предлагаемой продукции, различные виды оплаты и доставки, позволят Вам сэкономить время и получить максимум выгоды от сотрудничества с нами!

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Перечень производителей, продукцию которых мы поставляем на российский рынок

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С удовольствием будем прорабатывать для Вас поставки всех необходимых компонентов по текущим запросам для скорейшего выявления групп элементов, по которым сотрудничество именно с нашей компанией будет для Вас максимально выгодным!

С уважением,

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